7th Generation IGBT Module T/T1-Series Application Note

NX Type & std Type

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1. Features of the 7th Generation Module



In recent years, demand for industrial equipment such as general purpose inverters, elevators, uninterruptible power supply units (UPS), wind power / photovoltaic power generation, servo amplifiers and similar has been increasing more and more as the demand for more efficient energy use and longer life of equipment is increasing. In order to realize power consumption and high reliability, we developed "IGBT module T series (NX type, std type)" with the 7th generation IGBT and diode mounted and improved internal structure of the package. The T series realizes reduction of power loss, compact and lightweight package, rich lineup, simplification of assembly process of applied products.

1) Reduced power loss of the applied products

The 7th Generation chipset features new thinner IGBT chips and RFC diode chips (1200 V products, 1700V product). By adopting the 7th Generation chipset, it is possible to reduce the power loss of the applied products.

2) Compact and lightweight package with new package structure, rich lineup

In the 7th generation IGBT module, a new structure is adopted for NX and std type respectively. In the NX type, a resininsulated copper baseplate with an insulating part and a base part integrated is adopted, and the solder between the insulating part and the base part which was necessary in the conventional product is not used. DP (Direct Potting) resin is used as an internal filler. In the std type, the internal structure of the main electrode is laminated and a thick copperceramic-copper base plate is adopted. Both NX and std types have low inductance that reduces by 30% compared to conventional models by optimizing the internal layout of the module. Both NX and std type offer an extensive line-up of 650V, 1200V and 1700V breakdown voltage.

3) Simplification of the assembly process of the applied products

Optional pre-applied phase change thermal interface material (PC-TIM) makes it possible to eliminate the grease coating process. In addition, the NX type offers optional press-fit pins to eliminate the soldering process to the control board. Thus, it is possible to simplify the assembly process of the applied products.

3

1.1. Features of the 7th Generation IGBT and Diode Chip

In order to realize the reduction of the on-state loss and the switching loss leading to the improvement of the energy saving performance of the product, the 7th generation charge storage type IGBT (CSTBT [™]) and MOS (Metal Oxide Semiconductor) chip structure has been optimized using thinner wafers. The 7th generation diode chip has been made with thinner wafer and has applied the RFC (Relaxed Field of Cathode) structure using backside diffusion layer formation technology.

※ CSTBT[™]: Our proprietary IGBT utilizing carrier accumulation effect

X RFC diode: P layer is partially added on the cathode side, holes are injected at the time of recovery, and by making the recovery waveform soft the diode can suppress the rise of steep voltage

Reduction of on-voltage (V_{CEsat}) and turn-off loss (Eoff)

Figure 1-1 shows the trade-off characteristic comparison (1200 V withstand voltage) between the 7th generation IGBT and the conventional 6th generation with on-voltage (V_{CEsat}) and turn-off loss (E_{off}). The 7th generation IGBT reduces the ON voltage by about 0.2 V and the turn-off loss by about 7% compared with the 6th generation IGBT.

The IGBT chip improves the trade-off characteristic of this on-voltage and turn-off loss with every generation. In the 7th generation IGBT chip, this trade-off has been improved by making thinner wafers and optimizing the surface structure.



Figure 1-1. Tradeoff Comparison

Improved controllability of turn off loss (Eoff) and dv/dt (off) by R_G

The IGBT module can control the switching speed by changing the external gate resistance RG. The 7th generation IGBT module improves the controllability of turn off loss (Eoff) and dv/dt (off) by this RG.



Figure 1-3. Turn-off waveforms (CM450DX-24T)

1.2. Packaging Technology



* Comparison between CM600DX-24T and CM600DX-24S1

 Internal structure of the 7th generation module (NX type) A resin insulated copper base board with an insulating part and a base part integrated is adopted, and the solder between the insulation part and the base part which was necessary in the conventional product is not used. In addition, DP resin is used instead of general gel for filler.

Compatible and light weight package

We adopted a conventional NX type compatible package and reduced the weight by 15% by a new internal structure. In addition, by increasing the thickness and width of the copper circuit pattern inside the module and by using an optimized single substrate structure instead of multiple conventional insulating substrates, the chip mounting area is expanded to improve the rated current in the same package.

• Press-fit pin compatible

By applying press-fit terminals on the top of the module into the through holes of the control board, it is possible to connect all at once. This eliminates the need for soldering the module terminals to the control board through holes, thus simplifying the assembly process. For details, please refer to the application note for press-fit pins.

• PC-TIM (option)

It is possible to eliminate grease application step by pre-application of PC-TIM (Phase Change Thermal Interface Material) to the back side of the product. For details, refer to the application note of PC-TIM.



* Comparison with CM600DY-24S and CM600DY-24T

Internal structure of the 7th generation module (std type)

The 7th generation module adopted a thick copper-ceramic-copper baseplate without using solder between insulation part and baseplate which was necessary in conventional products. In addition, the ultrasonically (US) bonded terminal electrode is used as the main electrode instead of the conventional aluminum wire connection, and in some packages, the parallel plate structure is adopted.

Compact, lightweight package

By adopting a single substrate structure and a US bonding technology, we have expanded the chip mounting area and improved the rated current in the same package. The 600A/1200V product, is replaced with a 20% smaller package size and the weight is reduced by 55% compared to the 6th generation.

• PC-TIM applicable (option)

It is possible to eliminate grease application step by pre-application of PC-TIM (Phase Change Thermal Interface Material) to the back side of the product. For details, refer to the application note of PC-TIM.

1.3. Structure (Parts and Materials)

NX type

The structure diagram of CM150RX-13T is shown as a representative example.



* This figure shows the structural diagram of a typical example for the material explanation. It does not indicate the exact package size and chip size layout. There are also parts that are not in use in some packages.

	Parts	Material	Flame Retardance
1	IGBT chip	Silicon	
2	Diode chip	Silicon	
3	Common substrate	Insulating part: Resin	UL 94V-0
	(Insulating Metal Baseplate)	Baseplate: Copper	
4	Wire	Aluminum	
5	Case	PPS	UL 94V-0
6	Encapsulation	Epoxy resin	UL 94V-0
7	Adhesive	Epoxy resin	
8	Main terminal	Main material: Copper (Cu) Plating: Nickel (Ni)	
9	Control terminal	Main material: Copper (Cu) Plating: Tin (Sn), Base Plating: Nickel(Ni)	
-	Bushing (Heatsink mounting part)	Steel	

std type

The structure diagram of CM 300DY-13T is shown as a representative example.



* This figure shows the structure diagram of a representative for the material description. It does not indicate the exact package size and chip size layout. There is also parts that are not in use in some packages.

	Parts	Material	Flame Retardance
1	IGBT chip	Silicon	
2	Diode chip	Silicon	
3	Common substrate	Insulating part: Si ₃ N ₄	
	(Thick Metal Substrate)	Base: Copper	
4	Wire	Aluminum	
5	Case	PPS	UL 94V-0
6	Lid	PPS	UL 94V-0
7	Encapsulation	Silicone gel	
8	Adhesive	Silicone	
9	Main terminal	Main material: Copper (Cu) Plating: Nickel(Ni)	
10	Control terminal	Main material: Copper (Cu) Plating: Nickel(Ni)	
11	Bushing	Steel	
12	Self-tapping screws	Steel	

2. Glossary 2.1. Common

Item		Description	
IGBT	Insulated Gate Bipolar Transistor	Insulated gate bipolar transistor	
FWD	Free Wheeling Diode	Free wheel (flywheel) diode	
IPM	Intelligent Power Module	Intelligent power module	
t _{dead}	Dead time	Pause (no signal) time provided in the ON signal between the upper and lower arm transistors	
PC	Optocoupler	Optocoupler	
CMR	Common Mode Rejection	The maximum rise rate of the input-to-output common-mode voltage of the optocoupler	
СМН		The maximum rise rate of common-mode voltage between input and output that the preset high level can be maintained	
CML		The maximum rise rate of common-mode voltage between input and output that the preset low level can be maintained	
CTR	Current Transfer Ratio	The ratio of output current to input LED current of the optocoupler	
UL	Underwriters Laboratories	One of the safety standards in the United States. American Insurer Safety Test Laboratory certified. UL certified products of Mitsubishi power module conform to UL 1557.	
RoHS Directive	Restriction of Hazardous Substances (Original) DIRECTIVE 2002/95 / EC OF THE EUROPEAN PARLIAMENT AND OF THE COUNCIL of 27 January 2003 on the restriction of the use of certain hazardous substances in electrical and electronic equipment.	Regulations prohibiting the use of four heavy metals and two types of brominated flame retardants in electrical products. "The basic concept is to make the use of heavy metals of lead, mercury, cadmium, hexavalent chromium and new bromide flame retardants PBB and PBDE to new products of electrical equipment as a rule not to contain by July 1, 2006." WEEE: waste electrical and electronic equipment	
PC-TIM	Phase Change - Thermal Interface Material	High thermal conductivity grease. Solid phase at normal temperature and softening with temperature rise	
DP resin	Direct Potting Resin	A specially prepared resin material with enhanced coefficient of thermal expansion and adhesion	
US bonding	Ultrasonic Bonding	Ultrasonic bonding	
PressFit		A system that completes assembly by inserting the press-fit terminal into the through hole of the printed circuit board and eliminates the need for soldering	
RFC Diode	Relaxed Field of Cathode Diode	A P layer is partially added on the cathode side, a hole is injected at the time of recovery, and the recovery waveform is made soft so that the transient voltage rise can be suppressed by the diode	
CSTBT™		Our proprietary IGBT utilizing carrier accumulation effect	

2.2. Maximum ratings

Symbol	Item	Definition or description
V _{CES}	Collector-emitter voltage	Maximum voltage that can be applied for a short time between the collector and the emitter with the gate and emitter short circuited.
V _{GES}	Gate-emitter voltage	Maximum voltage that can be applied for a short time between the gate and emitter with the collector-emitter short circuited.
V _{RRM}	Maximum repetitive reverse voltage (Between anode and cathode)	Maximum voltage that can be applied for a short time between the anode and cathode of the clamping diode.
Vcc	Power-supply voltage	DC supply voltage that can be applied between the collector and the emitter.
lc	Collector current	Maximum current that can flow continuously from the collector to the emitter within the rated junction temperature range.
ICRM	Collector current (Maximum)	Maximum current that can be repeatedly flowed from the collector to the emitter in a short time within the rated junction temperature range. Normally it is twice the I_c .
IE	Emitter current	Maximum current that can flow continuously from emitter to the collector (freewheel diode) within the rated junction temperature range.
I _{ERM}	Emitter current (Maximum)	Maximum current that can be repeatedly flowed from the emitter to the collector (freewheel diode) in a short time within the rated junction temperature range. Normally it is twice the I_E .
IF	Forward current	Maximum current that can flow continuously from the anode of the clamp diode to the cathode within the rated junction temperature range.
Ifrm	(Maximum) forward current	Maximum current that can be repeatedly flowed from the anode of the clamp diode to the cathode in a short time within the rated junction temperature range. Normally it is twice the I_{F} .
Ptot	Collector loss	The maximum allowable power loss of the IGBT at the specified case temperature.
T _{stg}	Storage temperature	Maximum allowable temperature and minimum allowable temperature in the ambient temperature range when storing without applying power.
Visol	Insulation withstand voltage	The maximum voltage that can be applied between the terminal and the base plate in a state where the main terminal and the control terminal are collectively short-circuited. It is usually expressed as an effective value.
Mt	Tightening torque	Tightening torque range of terminal screws.
Ms	Tightening torque	Tightening torque range of the mounting screws.
T _{vjop}	Continuous operating junction temperature	Allowable temperature range of chip in continuous operation.
T _{vjmax}	Maximum junction temperature	The maximum temperature that the chip can tolerate in instantaneous operation such as overload.

2.3. Temperature ratings

Symbol	Item	Definition or description
Ta	Ambient temperature	When self-cooling or air cooling, the air temperature of a point which is not influenced by the heating element.
Tc	Case temperature	Temperature at a defined point on the enclosure (base plate) of the device.
Ts	Heat sink temperature	Temperature at a defined point on the heat sink.

2.4. Thermal ratings and characteristics

Symbol	Item	Definition or description
R _{th}	Thermal resistance	A value that indicates how many degrees K per unit electric power the junction temperature will rise over the externally specified point when the heat flow due to the power consumption of the junction is in equilibrium.
R _{th(j-c)}	Thermal resistance	Thermal resistance from junction (chip) to the case (base plate) surface.
Rth(c-s)	Contact thermal resistance	Thermal resistance from the surface of the case (base plate) to the surface of the heat sink. Normally, it is the value when thermal conductive grease is applied.

2.5. Electrical characteristics

Symbol	Item	Definition or description
I _{CES}	Collector-emitter cutoff current	The leakage current which flows upon application of a specified voltage between the collector and emitter while short-circuiting the gate and emitter.
IGES	Gate-emitter leakage current	The leakage current which flows upon application of a specified voltage between the gate and emitter while short-circuiting the collector and emitter.
V _{GE(th)}	Gate – emitter threshold voltage	Under specified conditions, the gate-emitter voltage required to supply the specified collector current.
V _{CEsat}	Collector – emitter saturation voltage	Collector-emitter voltage when specified collector current is supplied under specified conditions.
Cies	Input capacitance	Capacitance inside the device as seen from between the gate and emitter terminals, under the prescribed conditions, in a state where the collector and the emitter are short-circuited in an AC manner.
Coes	Output capacitance	Capacitance inside the device as seen from the collector-emitter terminal, under the prescribed conditions, in a state where the gate and the emitter are short-circuited in an AC manner.
Cres	Feedback capacitance	Capacitance inside the device as seen from between the collector and gate terminals, under the specified conditions, in a state where the collector and the emitter are short-circuited in an AC manner.
t _{d(on)}	Turn-on delay time	During turn-on, the time from 0% of the gate voltage until the collector current rises to 10% of the final value.
tr	Rise time	During turn-on, the time until the collector current rises from 10% of the final value to 90%.
t _{d(off)}	Turn-off delay time	During turn-off, the time from 90% of the gate voltage until the collector current falls to 90% of the initial value.
t _f	Fall time	At turn-off, the time from when the initial collector current drops to 90% until the time when it drops to 10%.
trr	Reverse recovery time	Time during which the reverse recovery current flows, at specified conditions, when the current of the built-in freewheeling diode is switched from the forward direction to the reverse direction.
Qrr	Reverse recovery charge	The charge accumulated in the internal elements, at specified conditions, when the current of the built-in freewheeling diode is switched from the forward direction to the reverse direction. Time integral of the reverse recovery current that flows in the reverse direction.
VEC	Emitter to collector voltage	Voltage drop when a specified current is passed through the built-in free wheel diode.
R _G	External gate resistance	The allowable range of the gate resistance connected between the element and the drive circuit.
Eon	Turn-on energy (Turn-on loss)	The time integral value of the product of the collector current and the collector- emitter voltage from the moment the collector current rises to 10% of the final value at the turn-on until the collector-emitter voltage drops to 10% of the initial value.
E _{off}	Turn-off energy (Turn-off loss)	The time integral value of the product of the collector current and the collector- emitter voltage from the moment when the collector-emitter voltage rises to 10% of the final value at the turn-off until the collector current drops to 2% of the initial value.
Err	Reverse recovery energy (Reverse recovery loss)	The time integral value of the reverse recovery current and the emitter-collector voltage, at turn-on, from the point when the forward current of the diode reaches 0A until the point where the reverse recovery current reaches the peak current until 0A is reached.

X The symbols and definitions are subject to change due to

revision of the reference standard (IEC, JEC).

3. Product label information

3.1. Configuration of the part number



Withstand voltage class (50 times the number rated VCES)

Withstand voltage class	V _{CES} (V)	
13	650	
24	1200	
34	1700	

Connection (There is no display on the label)



3.2. Labeling



- This product complies with the RoHS Directive (2011/65/EU).
- Restriction of the use of certain hazordous substance in electrical and eltronic equipment.

2 Lot number configuration



3 Module Nomenclature (example for 2 elements)



3.3. Two-dimensional barcode configuration

Two-dimensional code specifications

specification

Item	Specification
Code type	Data Matrix (ECC200)
Data type	Alphanumeric characters
Error correction	20 to 35%
Symbol size	6.0 mm × 6.0 mm
Code size	24 cell × 24 cell
Cell size	0.25 mm
Data capacity	39-digit

Data Example

Item	Characters count	
Model	1-20	
space	21-22	
Lot number	23-30	
space	31	
Parallel specification	32-34	
Space	35	
Serial	36-38	
space	39	
total	39	

Data Example

 1
 2
 3
 4
 5
 6
 7
 8
 9
 10
 11
 12
 13
 14
 15
 16
 17
 18
 19
 20
 21
 22
 23
 24
 25
 26
 27
 28
 29
 30
 31
 32
 33
 34
 35
 36
 37
 38
 39

 C
 M
 4
 5
 0
 D
 X
 2
 4
 T
 SP
 SP

"SP" represents a space (blank = equivalent to ASCII code number 32).

Application Note

Dual Module, PKG size 152x62mm

Dual Module, PKG size 137x110mm

6-pack, PKG size 122x62mm

Line up (List of available parts) 4.

7th -generation T Series NX type

VCES	Type name		Number	PKG size
(V)	Solder pin	PressFIT	elements	(Unit: mm)
	CM300DX-13T	CM300DXP-13T		
	CM450DX-13T	CM450DXP-13T	2	152 × 62
	CM600DX-13T	CM600DXP-13T		
	CM100TX-13T	CM100TXP-13T		
	CM150TX-13T	CM150TXP-13T	6	122 × 62
	CM200TX-13T	CM200TXP-13T		
650	CM150RX-13T	CM150RXP-13T	-7	407
	CM200RX-13T	CM200RXP-13T		137 × 77.1
	CM50MXUB-13T	CM50MXUBP-13T		
	CM75MXUB-13T	CM75MXUBP-13T		107.5 × 45
	CM100MXUB-13T	CM100MXUBP-13T	CIB	
	CM100MXUD-13T	CM100MXUDP-13T		100
	CM150MXUD-13T	CM150MXUDP-13T		122 × 62
	CM225DX-24T	CM225DXP-24T		
	CM300DX-24T	CM300DXP-24T		450
	CM450DX-24T	CM450DXP-24T	2	152 × 62
	CM600DX-24T	CM600DXP-24T		
	CM1000DX-24T	CM1000DXP-24T		137 × 110
	CM100TX-24T	CM100TXP-24T		
	CM150TX-24T	CM150TXP-24T	6	122 × 62
4000	CM200TX-24T	CM200TXP-24T		
1200	CM100RX-24T	CM100RXP-24T	7	407 77 4
	CM150RX-24T	CM150RXP-24T	/	137 × 77.1
	CM35MXUA-24T	CM35MXUAP-24T		
	CM50MXUA-24T	CM50MXUAP-24T		107.5 × 45
	CM75MXUB-24T	CM75MXUBP-24T		
	CM75MXUC-24T	CM75MXUCP-24T	CIB	
	CM100MXUC-24T	CM100MXUCP-24T		122 × 62
	CM150MXUD-24T	CM150MXUDP-24T		
	CM225DX-34T	CM225DXP-34T		
	CM300DX-34T	CM300DXP-34T	0	450 00
4700	CM450DX-34T	CM450DXP-34T	2	152 × 62
1700	CM600DX-34T	CM600DXP-34T]	
	CM100TX-34T	CM100TXP-34T	e	100 % 60
	CM150TX-34T	CM150TXP-34T	Ø	122 × 62

Ver.1.4

CIB (UC), PKG size 107.5×45mm

11, 111,



CIB (UD), PKG size 122×62mm



CIB (UB), PKG size 107.5×45mm







7-pack, PKG size 137x77.1mm

CIB (UA), PKG size 107.5×45mm



<IGBT module> 7th Generation T/T1 Series NX type / std type

7th -generation T series std type

V _{CES} (V)	Type name	Number of elements	PKG size (Unit: mm)	
	CM100DY-13T			
	CM150DY-13T		94 × 34	
650	CM200DY-13T			
030	CM300DY-13T		04 × 48	
	CM400DY-13T		94 ^ 40	
	CM600DY-13T		108 × 62	
	CM100DY-24T		04×34	
	CM150DY-24T		94 ^ 34	
	CM200DY-24T		0.4×4.9	
1200	CM300DY-24T	2	94 ^ 40	
1200	CM450DY-24T	2		
	CM600DY-24T		109 × 62	
	CM450C1Y-24T		106 × 02	
	CM600C1Y-24T			
	CM75DY-34T		04×24	
	CM100DY-34T		94 ^ 34	
1700	CM150DY-34T		0.4×4.9	
1700	CM200DY-34T		94 * 40	
	CM300DY-34T		109 × 62	
	CM400DY-34T		108 × 62	

Dual Module, PKG size 94x34mm



Dual Module, PKG size 94x48mm



Dual Module, PKG size 108x62mm



/ Series NX type / std type

Application Note

7th -generation T1 series

VCES	Part	Number	PKG size		
(V)	Solder pin	PressFIT	elements	(Unit: mm)	
	CM50MXUB-13T1	CM50MXUBP-13T1			
	CM75MXUB-13T1	CM75MXUBP-13T1		107.5 × 45	
650	CM100MXUB-13T1	CM100MXUBP-13T1	CIB		
	CM100MXUD-13T1	CM100MXUDP-13T1		100 × 60	
	CM150MXUD-13T1	CM150MXUDP-13T1		122 ^ 02	
	CM225DX-24T1	CM225DXP-24T1			
	CM300DX-24T1	CM300DXP-24T1		152 × 62	
	CM450DX-24T1	CM450DXP-24T1	2		
	CM600DX-24T1	CM600DXP-24T1			
	CM800DX-24T1	CM800DXP-24T1			
1200	CM35MXUA-24T1	CM35MXUAP-24T1			
	CM50MXUA-24T1 CM50MXUAP-24T1			107.5 × 45	
	CM75MXUB-24T1	CM75MXUBP-24T1			
	CM75MXUC-24T1	CM75MXUCP-24T1	CID		
	CM100MXUC-24T1	CM100MXUCP-24T1		122 × 62	
	CM150MXUD-24T1	CM150MXUDP-24T1			

Dual module, PKG size 152x62mm



CIB (UA), PKG size 107.5x45mm



CIB (UB), PKG size 107.5x45mm



CIB (UC), PKG size 122x62mm



CIB (UD), PKG size 122x62mm



5. Application

5.1. Example of application to a general-purpose inverter

System Block Diagram



a.AC220V power

Applicable Motor Rating	Inverter IGBT Module			
(kW)	NX Type	std Type		
11	CM100TX-13T	CM100DY-13T x3		
15	CM150TX-13T	CM150DY-13T x3		
18.5	CM150TX-13T	CM150DY-13T x3		
22	CM200TX-13T	CM200DY-13T x3		
30	CM200TX-13T	CM200DY-13T x3		
37	CM300DX-13T x3	CM300DY-13T x3		
45	CM450DX-13T x3	CM400DY-13T x3		
55	CM450DX-13T x3	CM400DY-13T x3		
75	CM600DX-13T x3	CM600DY-13T x3		

The NX type, 7in1 type (RX) with a built-in Brake element and CIB type (MX) with a built-in Brake element and Converter element is also available in some current ratings.
 The NX type, press-fit pin type (-P) is also available in all of the current ratings.

b.AC440V power

Applicable Motor Rating	Inverter IGBT Module	
(kW)	NX Type	std Type
15	CM100TX-24T	CM100DY-24T x3
18.5	CM100TX-24T	CM100DY-24T x3
22	CM100TX-24T	CM100DY-24T x3
30	CM150TX-24T	CM150DY-24T x3
37	CM200TX-24T CM225DX-24T x3	CM200DY-24T x3
45	CM200TX-24T CM225DX-24T x3	CM200DY-24T x3
55	CM300DX-24T x3	CM300DY-24T x3
75	CM300DX-24T x3	CM300DY-24T x3
90	CM450DX-24T x3	CM450DY-24T x3
110	CM450DX-24T x3	CM450DY-24T x3
132	CM600DX-24T x3	CM600DY-24T x3
160	CM1000DX-24T x3	-

%The NX type, 7in1 type (RX) with a built-in Brake element and CIB type (MX) with a built-in Brake element and Converter element is also available in some current ratings.

%The NX type, press-fit pin type (-P) is also available in all of the current ratings.

5.2. Example of application to a general-purpose servo amplifier

System Block Diagram



a. AC220V power

Applicable Motor Rating	Inve IGBT M	rter lodule
(kW)	NX Type	std Type
3	CM100TX-13T	CM100DY-13T x3
5	CM150TX-13T	CM150DY-13T x3
7.5	CM200TX-13T	CM200DY-13T x3
11	CM300DX-13T x3	CM300DY-13T x3
15	CM450DX-13T x3	CM400DY-13T x3
22	CM600DX-13T x3	CM600DY-13T x3

The NX type, 7in1 type (RX) with a built-in Brake element and CIB type (MX) with a built-in Brake element and Converter element is also available in some current ratings.
 For NX type, press-fit pin type (-P) is also available in all of the current ratings.

b. AC440V power

Applicable Motor Rating	Inverter IGBT Module			
(kW)	NX Type	std Type		
5	CM100TX-24T	CM100DY-24T x3		
7.5	CM100TX-24T	CM100DY-24T x3		
11	CM150TX-24T	CM150DY-24T x3		
15	CM200TX-24T CM225DX-24T x3	CM200DY-24T x3		
22	CM300DX-24T x3	CM300DY-24T x3		
30	CM450DX-24T x3	CM450DY-24T x3		
37	CM450DX-24T x3	CM450DY-24T x3		
45	CM600DX-24T x3	CM600DY-24T x3		

The NX type, 7in1 type (RX) with a built-in Brake element and CIB type (MX) with a built-in Brake element and Converter element is also available in some current ratings.

%For NX type, press-fit pin type (-P) is also available in all of the current ratings.

5.3. Example of application to PV / UPS

System Block Diagram



a.650V elements

Applicable Capacity	Inverter IGBT Module		
(kW)	NX Type	std Type	
3.3	CM100TX-13T	CM100DY-13T x3	
5.5	CM100TX-13T	CM100DY-13T x3	
10	CM150TX-13T	CM150DY-13T x3	
20	CM200TX-13T	CM200DY-13T x3	
30	CM300DX-13T x3	CM300DY-13T x3	
50	CM450DX-13T x3	CM400DY-13T x3	
100	CM600DX-13T x3	CM600DY-13T x3	

% For NX type, 7in1 type (RX) with a built-in Brake element is also available in some current ratings. % For NX type, press-fit pin type (-P) is also available in all of the current ratings.

b.1200V elements

Applicable Capacity	Inve IGBT N	rter Iodule
(kW)	NX Туре	std Type
5.5	CM100TX-24T	CM100DY-24T x3
10	CM100TX-24T	CM100DY-24T x3
20	CM100TX-24T	CM100DY-24T x3
30	CM150TX-24T	CM150DY-24T x3
50	CM300DX-24T x3	CM300DY-24T x3
100	CM600DX-24T x3	CM600DY-24T x3

% For NX type, 7in1 type (RX) with a built-in Brake element is also available in some current ratings. % For NX type, press-fit pin type (-P) is also available in all of the current ratings.

6. Safety standard (UL Standard)

Mitsubishi Power Modules are UL certified (Recognized) for UL Standard 1557 and Category Code QQQX2. (Except for some special items, File No. E 323585)

Power modules are not certified for other safety standards (TUV, VDE, CSA etc). (Reinforcement of CE marking is not made considering correspondence to insulation.) Regarding European CE and China CCC, as of October 2016, the target regulation as a power module has not been confirmed. The authentication by part number can be checked on UL's website. Please refer to the following procedure.

1. Visit the UL website (https://www.ul.com) and click on "Online Certifications Directory" or type the following address into your browser:

http://database.ul.com/cgi-bin/XYV/template/LISEXT/1FRAME/index.htm

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2. Enter the file number "E323585" in the UL File Number field displayed on the search screen and click the SEARCH button.

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MITSUBISHI ELECTRI	C CORP Electrically Iso	olated Semiconductor De	vices - Component	QQQX2.E3235
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Electrically-isolated semiconductor devices, ""PM Series"", Model(s) PM100CS1D060-NW, PM150CS1D060-NW, PM450RGC PM75CS1D060-NW Electrically-isolated semiconductor devices, "CM-S Series and RM-S series.", Model(s) RM150DX1-24S, RM200DX1-24S, RM300DX1-24S
Electrically-isolated semiconductor devices, Model(s) CM1000DX-24T, CM1000DXP-24T, CM1000HA-34S, CM100DY-13T, CM100DY-24T, CM100DY-34T, CM100RX-24T, CM100RXP-24T, CM100TX-13T, CM100TX-24T, CM100TXP-13T, CM100TXP-24T, CM100TXP-24T, CM100TXP-24T, CM100TXP-24T, CM150RX1-24T, CM150RXP-24T, CM150PX-13T, CM150DY-24T, CM150RX-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150RXP-24T, CM150TXP-13T, CM150TXP-24T, CM200DY-13T, CM200DY-24T, CM200DY-34T, CM200RX-13T, CM200RXP-13T, CM200TXP-13T, CM200TXP-13T, CM200TXP-24T, CM200DY-24T, CM200DY-24T, CM200DXP-24T, CM200DXP-24T, CM300DXP-24T, CM200DXP-24T, CM200DXP-24T, CM300DY-24T, CM200DXP-24T, CM300DY-24T, CM300DY-24T, CM300DY-34T, CM300SY1N-34S, CM300SY1P-34S, CM400DX-13T, CM400DX-24T, CM400DXP-13T, CM400DXP-24T, CM400DY-34T, CM400DXP-24T, CM400DXP-13T, CM400DXP-24T, CM400DY-34T, CM400DXP-24T, CM400DX-13T, CM400DX-24T, CM400DXP-13T, CM400DXP-24T, CM400DY-24T, CM500C2Y-24S, CM600C1Y-24T, CM600DX-13T, CM600DX-24T, CM600DXP-24T, C

- X There may be no result of the part number even if the product is certified due to the procedure used to list the part numbers. If you cannot find the part number, please contact the semiconductor sales department of your local Mitsubishi Electric branch.
- X Currently, we do not offer it as a yellow card.
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Handling Precautions Elements of a power module may be damaged depending on usage conditions (electrical / mechanical stress, handling, etc.). In order to use our power module safely, observe the following precautions and use correctly.

7.1. Handling Precautions

During transportation, please keep the shipping box in the correct orientation. If it is inverted or excessive force is applied, the terminals may be deformed or the resin case may be broken. Throwing or dropping may cause the device to break. Care should be taken when transporting during rainfall or snowfall to not expose the device to water. Do not use the device if it is exposed to water as it may malfunction at the time of use.
The temperature and humidity of the storage location is desirably within the normal temperature and humidity range of 5 - 35°C and 45 - 75%. If stored in a more extreme environment than this temperature and humidity, the performance and reliability of the device may decrease.
When storing the product for a long term (over 1 year), please take measures for dehumidification. In addition, please confirm that there is no scratch, dirt, rust etc. on the device when using after long term storage.
Use in environments where high humidity (including condensation), organic solvents directly adhere, where corrosive gas is generated, or in places where explosive gas, dust, salt, etc. are present may cause serious accidents. Please avoid usages in these environments.
For the epoxy filled resin and case material, UL standard 94V-0 certified products are used. It is not incombustible, so please use caution.
 Please observe the following items in order to prevent damage due to static electricity. 1) Precautions to prevent static electricity destruction If static electricity charged on the human body and packing materials becomes an excessive voltage (±20V or more) and is applied between the gate and the emitter, the device may be damaged. The basic principle of static electricity countermeasure is to minimize the generation of static electricity and to avoid application of the voltage to the device.
 * Do not use containers that are susceptible to static electricity for transportation and storage. * It is recommended to short-circuit the gate and emitter with carbon cloth/foam etc. until just before using the module. Also, please wear gloves so as not to touch the terminals with bare hands. Avoid gloves and work clothes that are easy to charge, such as nylon. * During assembly, ground the equipment to be used and the person performing work. It is also recommended to ground a conductive mat on the surface of the work table and the floor around the work table. Assembly refers to the point in time when the product is removed from the packing box. * Please note that when the gate-emitter is open on the printed circuit board on which the element is mounted, it may be destroyed by the static electricity charged on the printed circuit board. * When using a soldering iron, use a low voltage (12 V to 24 V) soldering iron for semiconductors, Ground the tip. (2) Open Gate-emitter Guidelines * Do not apply voltage between the collector and the emitter while the gate and emitter are open.
[- (- (-) - (



7.2. Flame Retardance

NX type

The case/encapsulation material PPS/resin and insulating substrate material used in the IGBT module have a flame retardance complying with UL 94 V-0 and have self-extinguishing properties. If the module is cut off from the combustion source, there is no danger of spreading fire. Other components such as the silicon chip, copper baseplate, etc. do not have applicable UL flame retardance standards.

std type

Since the PPS used for the case and lid of the IGBT module has flame retardance conforming to UL 94 V-0 and has self-extinguishing properties, there is no danger of spreading fire if the combustion source is cut off. Silicone gel is flammable and does not comply with UL 94 V-0. Products with characteristics with a flash point of 340°C, an ignition point of 450°C, and dielectric breakdown strength after curing of 10 kV/mm or more are used. Also, there is no self-extinguishing property, so in case of fire, it is necessary to extinguish by using powder fire extinguisher, carbon dioxide extinguishing agent, foam extinguishing agent etc.

Other components such a silicon chip, copper baseplate, etc. do not have applicable UL flame retardance standard.

Precautions on Actual use 8.

8.1. Method of attaching the module to the heat sink



Note: Please judge the decision from user's side b decrease of thermal resistance performance in cas usage.	by deeply investigating possibility of any failure and se recommended condition is not kept by actual
 7th generation IGBT modules are offered to op - Thermal Interface Material) on the baseplate W/(m·K)) and it can be uniformly applied by p compared to grease and temperature rise can the "PC-TIM Application Note". 	otionally be pre-coated with PC-TIM (Phase Change e. Since PC-TIM has high thermal conductivity (3.4 rinting, contact thermal resistance decreases n be reduced. For details on handling, please refer to
 It is also possible to apply heat conductive grees surface between the module and the heat sind uniform with thickness of 50µm to 100µm. 	ease (herein referred to as grease) to the contact k. In this case, please apply so that it becomes
 If PC-TIM or grease is applied to the contact s corrosion of the contact parts. However, pleas operating temperature range and does not ch 	surface with the heat sink, it will also help prevent se use grease that does not deteriorate within the ange over time.
 Use a torque wrench for tightening and tighten too large, there is a danger of breakage or de components. 	n to the required torque. If the tightening torque is terioration of the element as well as the tightening
Grease coated surface Base plate edge Flatness specified area of heat sink	Flatness p-p ↓ ↓ ↓
Figure 8-3. Flatness of the heat sink	Figure 8-3-a. Flatness of the heat sink for std type

Required shape of the module mounting heatsink hole

The outermost diameter dimension of the threaded hole in Figure 8-4 (ΦA) as shown in Table 8-1 is recommended for securing the axial force of the mounting screw (to prevent screw looseness) and preventing stress concentration on the case resin material.



Figure 8-4.Schimatic of module mounting heatsink hole

Table 8-1. Recommended maximum outer diameter dimension of heat sink side threaded hole ϕA

PKG type	Mounting screw	The recommended maximum φA [mm]
NX type	M5	6
std type	M6	7

8.2. Power module implementation

Capacitor Connection

During switching, high voltage is induced in power circuit stray inductance by the high di/dt of the main current when the stray inductance is large. This voltage can appear on the IGBT module and cause IGBT or diode destruction. In order to avoid this problem, guidelines that should be followed in designing the circuit layout are:

- ① Reduce the L1 inductance by bringing the connection of the smoothing capacitor close to that of the module and arranging the return connection in a laminated plate structure to cancel the magnetic field.
- ② Connect the snubber capacitor close to the module terminal in order to bypass the high frequency current and absorb the surge voltage.
- ③ The smoothing capacitor itself should be of low impedance type.
- ④ Decrease the di/dt by slowing the switching speed of the element (increase the gate resistance, etc.).

It is a general measure to suppress the wiring inductance (L1) of the main circuit as much as possible by (1) or (3), and still suppress surge voltage using (2) or (4) when the surge voltage is large. Regarding (2), if the wiring inductance (L1) is large, the voltage oscillation may increase due to the resonance between C and L1. At that time, oscillation can be suppressed by changing the value of C.



Figure 8-5. Power Module application circuit

L1: Inductance of the wiring connecting the smoothing capacitor and the IGBT module. Since it is a round-trip line, it is necessary to use laminated conductors made of parallel flat metal plates sandwiching an insulator so that mutual magnetic fields are canceled.

L2: Inductance of the snubber capacitor lead wire. If this inductance is large, it will not be an effective bypass.

L3: Inductance of the wiring connecting the load.

Precautions for mounting/installation

Please install using hand tightening method when possible. When tightening with an electric screwdriver or similar, the excess thermally conductive grease should be squeezed out by pushing the module against the heat sink, etc. before tightening. Also, it is necessary to sufficiently lower the tightening speed or to apply a low viscosity grease. If tightening at high speed with a high viscosity thermally conductive grease, the module may deform and be damaged.

Note)

In case of PC-TIM, softening starts at 45°C or higher after mounting on heat sink.

Please use mounting screws and washers that match the module mounting hole size. If screws with a size smaller than the recommended screw size (with flat washer) are used, there is a possibility that a misalignment of the center line of the screw occurs, a shearing force is applied to the flat washer, and the clamping force is not evenly applied to the module mounting hole. This will cause loosening of the mounting screws. An attaching method that makes axial force uniform and that the head end face of the screw can be held within the center line deviation so as to cover the whole mounting hole is ideal.

When using iron screws for module installation and screw terminal connection, the tightening torque is limited by the strength of the resin case etc. of the module body. Please note that tightening with the standard tightening torque of the iron screw specified in JIS etc. may cause damage to the case.

Note)

Please note the screw length. If screws longer than necessary are used, it may cause resin breakage at the terminal. Please refer to the following dimensions and use the screw of the optimum length.



Terminal screw hole depth (Unit: mm, resin portion tolerance: ±0.3 mm)

Screw and size		Model		В	Terminal thickness
Main terminal	М5		13.5	5.2	0.8
					1.0
Main	MG		14.8	6.3	1.0
terminal	ΙΝΙΟ		14.4	7	1.5

*Dimensions A and B do not include floating of the terminal.

There are products with 2 terminals and 3 terminals as power terminals. Each external terminal is internally connected, but be sure to use all terminals for external connection. With only 1 of the terminals connected, the current capacity will be insufficient as the main terminal, and the temperature rise of the terminal may exceed the acceptable level of the product.

8.3. Stand-off recommended use (NX type)

Recommended use conditions

Recommended conditions for tightening the standoff screws to attach the printed circuit board are described below.

7 th g	generation recommended	screws		
	Thread type	Screw size	Tightening torque	Tightening Method
	B1 tapping screw	φ2.6x10	$0.75N_{m} \pm 10\%$	1. Manual method by hand (equivalent to
	B1 tapping screw	φ2.6x12	0.75N° III±10%	electric driver 30 rpm)
	PT [®] Screw	K25x8	0.55N [.] m±10%	2 Electric screwdriver 600 rpm or less
	PT [®] Screw	K25x10	0.75N [.] m±10%	
	DELTA PT OScrew	K25x8	0.55N [.] m±10%	
	DELTA PT OScrew	K25x10	0.75N [.] m±10%	

* PT® · DELTA PT® is a registered trademark of EJOT.

* 1 The above conditions are tightening conditions when printed circuit board thickness t=1.6mm.

- * 2 When considering other screws or when changing tightening conditions, please separately evaluate and check the acceptability.
- * 3 When using a high-speed tightening tool such as electric screwdriver, ensure it has performance that meets the recommended conditions and is regularly calibrated for both rotation speed and torque.
- * 4 The standoff may only be used 1 time and is not recommended to be reused.
- * 5 The above conditions may differ depending on usage environment etc. Please be sure to determine the conditions after actual evaluation.

Pin terminal

7th generation terminal specification

Item	Spec	ifications
Terminal Material	Copper(Cu)	
Disting two	Tin(Sn)	
Plating type	Bas	e: Nickel(Ni)
Plating	Sn	4~10µm
thickness	Ni	1~6µm

· Recommended soldering conditions Soldering by solder immersion (flow soldering)

Solder temperature	Immersion time
260°C±5°C	10 seconds±1 second

Soldering with a soldering iron (manual soldering)

Tip temperature		Heating time
	360°C±10°C	5 seconds±1 second

Press-fit

In addition to the conventional solder pin type, the NX type has a lineup of press-fit pin type that eliminates the need for soldering to the printed circuit board. (Model name: CM ** XP - ** T)

By inserting into the through hole at the prescribed pressure and speed, a metallic bond with the plating of the through hole part is made, and soldering becomes unnecessary. Care must be taken of suitable printed circuit boards, installation equipment / jigs, installation methods, etc.. For handling details please refer to the separate "Press Fit Application Note".

8.4. Thermally conductive (heat dissipating) grease application example

Method of applying the thermally conductive grease to the power module:

- ① Materials Required: Power module, thermally conductive grease, screen, electronic mass meter, gloves What is called a thermal compound basically performs the same function as the thermally conductive grease. When using a highly viscous compound, thoroughly stir before spreading so that it spreads over the entire baseplate.
- 2 The relationship between the amount and the thickness of the thermally conductive grease to be applied is as follows:

Thickness of thermally conductive grease= $\frac{\text{amount of grease [g]}}{\text{baseplate area of module [cm²] × density of grease [^g/_{cm³}]}}$

Our recommended thermal conductivity grease thickness is 50µm to 100µm. Note, this thickness is the initial value at the time of coating, it changes depending on the flatness of the base plate and heat sink after installation.

Calculate the amount of thermal conductive grease required for the power module. Calculation example: Mounting area 97 mm × 58 mm, for case of G-747 made by Shin-Etsu Chemical Co., Ltd. for heat conductive grease

 $50\mu m = \frac{\text{amount of grease [g]}}{56.26 \text{ [cm}^2\text{]} \times 2.65 \text{ [}^g/_{\text{cm}^3\text{]}}}$

 \therefore Thermally conductive grease amount \doteq 0.75 [g].

- ③ Measure the mass of the power module without grease applied.
- (4) Add the amount of thermally conductive grease calculated in (1) to the base plate of the power module using an electronic mass meter. There is no specific/required method for applying the grease.
- ⑤ Apply the added thermal conductive grease to the entire surface of the base plate so as to be uniform. There is no particular limitation on the application method as long as the target thickness is nearly uniform over the entire surface of the baseplate of the power module.
 - Please be careful not to contaminate with foreign matter and bubbles when applying the grease. When coating with a roller etc., please be careful that bubbles do not get mixed in the grease. When using metal spatula, please be careful not to scratch the baseplate surface. It is possible to reduce the aging effect of the thermally conductive grease on the baseplate by not wiping off the excess grease after installing to the heatsink.

Example of using a squeegee and mesh screen (mask) (Application example: Shin-Etsu Chemical Co., Ltd.)



Grease for aluminum conductor connections is mainly aimed at improving the contact properties of the aluminum surface and lowering electrical contact resistance by preventing corrosion. Although there seems to be a long-term use record, it is not intended to improve the heat conduction of the contact part, so it cannot be expected to make much reduction in contact thermal resistance. If this grease is adopted, sufficient heat dissipation design/study is required.

The optimum thermal conductivity grease varies depending on the application and usage, so please contact directly to the grease maker at the time of selection / specification.

8.5. Concept of thermal resistance

The module datasheet defines the thermal resistance $R_{th(j-c)}$ between the chip junction and case (baseplate) and the contact thermal resistance $R_{th(c-s)}$ between case (baseplate) and heat sink. The reference point of thermal resistance (case temperature) is just under the chip. Chip placement of each product is described in the data sheet. An example of that is described below.

Tr** indicates the center position of the IGBT chip, Di** indicates the center position of the FWD chip. For 2 elements, Tr1/Di1 indicates the upper arm and Tr2/Di2 indicates the lower arm.





Figure 8-6 Chip location (CM225DX-24T dual module)



Measure the base plate and heat sink temperature by attaching a thermocouple to the position (directly under the chip) shown in the figure.

<u>Notes</u>

- The thermal resistance of the heat sink will change depending on the material, area, and thickness used. Generally, with heat sinks of the same material, the smaller the area and the thinner the heatsink, the higher the thermal resistance.
- The contact thermal resistance R_{th(c-s)} shown in the data sheet is the typical value under noted application conditions of thermal conductive grease. The thermal conductivity conditions of the grease for the Rth(c-s) values are 0.9W/(m K) for NX type and 3.0W/(m K) for std type respectively. Actual contact thermal resistance varies depending on the type of grease, the applied amount and the heat generation conditions, so confirm (measure) with the grease and heat sink actually used and in actual operation conditions.
- · Water-cooled heat sink:

The general industrial power module is assumed to be used in a cooling system using a natural convection heatsink or air cooling heat sink. If you using a water-cooled heat sink, thermal resistance $R_{th(c-s)}$ and contact thermal resistance $R_{th(c-s)}$ may change significantly due to the nature of heat spreading. Further, if condensation occurs, discharge may occur between the main electrodes. Destruction due to dew condensation is possible due to overvoltage breakdown due to the surge voltage generated by the discharge. Since there is no dew condensation countermeasure as part of the module, it is necessary to take dew condensation measures in the unit using the module when it is used with water cooling. The sealing material (DP resin) filled in the module has moisture permeability.

• Package for general industrial power module is not airtight structure, so liquid can be absorbed by module. Both the package materials and semiconductor chips are not designed assuming long-term contact with anything other than the DP resin. Therefore, characteristics and reliability cannot be guaranteed when the module is immersed in silicone oil or similar.

Ver.1.4

Application Note

8.6. Example of thermocouple attachment

Example of thermocouple attachment for case temperature measurement just under the chip are shown below.

•Case temperature measurement

Case temperature just under chip is used for estimation of junction temperature. (Please see "10. Power loss and heat dissipation design" for the detail estimation procedure.) Thermocouple attachment examples for NX type and std type are shown below.

NX type

<Step 1>

Drill into the IGBT module as shown in Figure 8-8.

(The depth of the groove is 1mm, the width is 1mm as a guideline when a thermocouple with a wire diameter of 0.3mm (recommended value) is used.)

Please be careful that the base of the thermocouple tip (blue line) comes **Baseplate** to the point you want to measure (just under the chip).

<Step 2>

Insert a thermocouple into the groove drilled in Step 1, place it on the module baseplate, and seal with a high thermal conductivity filler from the top so that the thermocouple does not move

Figure 8-9 shows an example of groove drilling on the back of the module. Please be careful not to impact the flatness of the module by burrs and filling materials after the groove processing.







Figure 8-9: Drilling Example (NX type module back)



Figure8-10. Thermocouple attachment on std type baseplate



Figure 8-11: Drilling Example (std type module back)

Note) For the junction temperature estimation, it is recommended to measure the case temperature with a cooling system actually employed to your application. If heatsink temperature needed to be obtained, please refer the following example.

std type <Step 1>

Drill into the module as shown in Figure 8-8 (the depth of the groove is 0.4 mm the width is 0.3 mm as a guideline when a thermocouple with a

0.4mm, the width is 0.3mm as a guideline when a thermocouple with a wire diameter of 0.1mm (recommended value) is used. At this time, please be careful that the base of the thermocouple tip comes to the point you want to measure (just under the chip).

<Step 2>

Insert a thermocouple into the groove drilled in Step 1, place it on the module baseplate, and seal with a high thermal conductivity filler from the top so that the thermocouple does not move

Figure 8-11 shows an example of groove drilling on the back of the module. Please be careful not to impact the flatness of the module by burrs and filling materials after the groove processing.

Application Note

•Heatsink temperature measurement (NX type and std type common)

<Step 1>

Drill into the heat sink as shown in Figure 8-12.

(The depth of the groove is 1mm, the width is 1mm as a guideline when a thermocouple with a wire diameter of 0.3mm (recommended value) is used.

Please be careful that the base of the thermocouple tip (blue line) comes to the point you want to measure (just under the chip).

<Step 2>

Insert a thermocouple into the groove drilled in Step 1, place it on the heat ^{tip} sink, and seal it with a high thermal conductivity filler from the top so that the thermocouple does not move. It is no problem even if the thermocouple is caulked to the heat sink.

Figure 8-13 shows an example of groove processing on a heat sink. Be careful not to impact the flatness of the heat sink by burrs and filling materials after the groove processing.



Figure8-12 Example of heatsink thermocouple mounting



Figure 8-13: Drilling Example (heatsink)

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8.7. Snubber circuit

Snubber circuit application example

A snubber circuit application example is shown in Figure 8-15. The following is reference design values of the snubber inductance (L_2) and the snubber capacitor (C_s) in the application circuit. A waveform example of collector-emitter voltage V_{CE} in turn-off is shown in Figure 8-16. Here the total inductance L is defined as $2xL_1+2xL_2$.





Figure 8-15. Snubber circuit application example



In the circuit of Figure 8-15, at first, a surge voltage ($\Delta V_1 = 2 \cdot L_2 \cdot di/dt$) is generated by di/dt due to turning off the IGBT and wiring inductance (L₂) of the snubber capacitor (C_s). In order to suppress ΔV_1 , it is necessary to reduce the snubber wiring inductance L₂. Reference design values for snubber inductance are shown in Figure 8-17. As for di/dt, a tangent line is drawn on the current waveform of actual measured turn-off as a typical value. Since it may vary somewhat depending on the characteristics, snubber circuit wiring inductance (2·L₂) should be considered as a guideline and checked thoroughly by actual evaluation.

Next, when L₁ is sufficiently large, resonance occurs between L₁ + L₂ and the snubber capacitor (C_s), and its peak voltage ΔV_2 appears. In order to suppress ΔV_2 , it is necessary to increase the value of snubber capacitor C_s. Reference design values for snubber capacitance are shown in Figure 8-18. C_s is calculated by using the formula in the figure. I_{OFF} assumes the current flowing during short-circuit, and it is calculated as 5 times rated current.



Figure 8-17. Snubber capacitance - Collector current dependence

Calculation example of the snubber inductance (L₂)

Rated collector	Snubber inductance
current	2xL ₂ (nH)
100A	< 89 nH
200 A	< 54 nH
300 A	< 39 nH
450 A	< 28 nH
600A	< 22 nH
1000A	< 15 nH

Conditions: $\Delta V_1 = 150V$

Assumed di/dt in turn-off at rated collector current (Ic=rated, typ; $@T_{vi}{=}25^{\circ}C)$



Figure 8-18. Snubber inductance - Collector current dependence

Calculation example of Snubber Capacitance (Cs)

Rated collector	Total inductance	Snubber capacitance $Cs(\mu F)$
100A	< 100 nH	>1.1
200 A	< 50 nH	>2.2
300 A	< 30 nH	>3.0
450 A	< 20 nH	>4.5
600A	< 15 nH	>6.0
1000A	< 10 nH	>11.1

Conditions: $\Delta V_2 = 150V$

Assumed 5 times rated collector current

In the case of module parallel connection, it is recommended to attach a snubber circuit to each module individually. In the case of increasing snubber capacitance by paralleling snubbers, it is recommended to divide snubber circuit and attach those circuits to multiple modules. It is considered better for the snubber wiring inductance (L₂) reduction and the current capacity of the snubber.

Measures to reduce surge voltage

- ① Reduction of circuit inductance (L1, L2)
- Reduction A (6 and 7 packs): printed circuit board with lamination
- 100 A to 1000A (dual modules): Parallel flat (laminated) bus plates
- Snubber circuits
- 50 to 200A (6 and 7 packs): snubber circuit (a) or (b)
- ●(a)0 to 600A (dual module): snubber circuit (a) for each phase or (b) for each

phase

• f00A or more: snubber circuit (a) and (c) for each phase





Figure 8-19. Various snubber circuit examples

Table 8-2	Applicable	snubber	circuits
-----------	------------	---------	----------

Module	Applicable Snubber Circuit
NX type	a, b, or a + b,
std type	a, b, or c

Wiring example of the power module

It is suggested to layout by using two DC bus conductor plates (P layer, N layer) which are sandwiching an insulating layer. The stacking order has no effect on wiring inductance. An example of how to connect this multilayer bus to the module is shown below.



Figure 8-20. Example of NX type (dual module)

Figure 8-21. Example of std type (dual module)

Low inductance laminated bus bar Manufacturer example: Ryoden Kasei Co., Ltd.: "Laminated bus bar" http://www.ryoka.co.jp/

For details, please contact directly to the manufacturer.

8.8. Other

In the IGBT module, the insulation distance is designed to UL 840 as a reference standard, but there is a risk that the clearance might become insufficient at high altitude. Due to decreased air pressure, the withstand voltage for the same spatial distance decreases and the insulation capability decreases in general.

Also, as the altitude increases, the cosmic radiation will increase rapidly. It is known that as more cosmic radiation hits a semiconductor, the possibility of random failure increases. Please refer to application notes "About Isolation Voltage and LTDS".

9. How to use the IGBT module

9.1. IGBT Module Selection

(1) Voltage rating

The voltage rating of the IGBT module is determined by the input supply voltage of the applicable device or the bus voltage applied between P and N of the module. Generally, Table 9-1 shows the input power supply voltage, bus voltage, and rating of module.

	Voltage rating of the IGBT module						
	650V	1200V	1700V				
Input supply voltage (AC)	~ 240Vrms	~ 480Vrms	~ 690Vrms				
P-N bus voltage (DC)	~ 450V	~ 850V	~ 1200V				

Table 9-1 Application	example of	innut	nower su	nnlv	voltane	and	device	ratino
Table 9-1. Application	i example or	mput	power su	ppiy	/ vollage	anu	uevice	raung

(2) Current rating

It is a current value that can flow as a DC current. For switching operation (pulse), up to twice the rated current can be tolerated. However, in actual use, it is necessary to consider junction temperature, case temperature, life (lifetime of power cycle, thermal cycle etc) etc.

9.2. Recommended driving conditions and driving circuit

(1) Recommended driving conditions

The positive recommended gate voltage is $+V_{GE} = 15V\pm10\%$. If it is used under conditions above this recommended range, short circuit energy will increase by increasing the short circuit current, so it is necessary to shorten the time to shut off. Also, if it is lower than the recommended range, it is assumed that the operation will be in the active area, as shown in the output characteristics of the 7th generation IGBT (CM600DX-24T example) in Figure 9-1. When used in this active area, caution is necessary as there is a possibility of thermal destruction in a short time due to rapid temperature rise.



Figure 9-1. Output characteristics of the CM600DX-24T

Negative gate voltage is recommended $-V_{GE}$ =-15V due to dependence of reverse bias voltage and switching loss. Apply a reverse bias voltage that does not allow false turn-on by external noise or dv/dt.

(2) Drive circuit

Key points of gate drive circuit design of IGBT module are gate voltage, gate resistance and wiring. The basic form of the gate circuit is shown in Figure 9-2.



Figure 9-2. Basic form of the gate circuit

- Electrically isolate the IGBT module and the input signal by using an optocoupler. The optocoupler must be high speed with high noise immunity (high CMR).
- Be sure to design the buffer circuit to apply the positive and negative bias so that the gate current can flow sufficiently.
- Reduce the wiring between the gate drive circuit and the IGBT module as much as possible. Avoid noise induced from main circuit etc. by e.g. twisting a pair of the gate wiring and the emitter wiring. Do not bind up the gate wiring with the one for the other phases.
- When the load is short-circuited, the gate-emitter voltage V_{GE} rises and may break down due to the larger current flowing. Therefore, it is recommended to suppress surges of the gate-emitter voltage. An example is shown below in Figure 9-3.
- If a voltage is applied to the main circuit before the control voltage supply becomes stable, the IGBT module may be destroyed.
- In case a voltage is applied to the main circuit before the control voltage supply becomes stable, it is recommended to insert a resistor between the gate and the emitter. (Resistance value example: several kΩ to several tens of kΩ)
- Some optocoupler is available in market which can drive IGBT directly. Please contact the optocoupler or drive circuit manufacturer for the information.



Figure 9-3. Gate-emitter voltage surge clamp example

(3) Selection of gate resistance

As for the gate resistance RG, upper and lower are listed as recommended values in the data sheet. The lower recommended value is the gate resistance condition that regulates the electrical characteristic switching time of the IGBT module, and is the minimum resistance value assuming actual use conditions. The gate resistance RG greatly affects switching time and switching loss. Below is a graph of switching time vs. RG and switching loss vs. RG of CM600DX-24T.





Figure 9-5. Switching losses -R_G

It is necessary to select the optimum RG value from characteristics such as switching time, switching loss, surge voltage and so on. Optimum RG should be selected with careful confirmation for no occurrence of any maximum rating violation (Tvj, Vces, etc.) or any unexpected malfunction (arm-shoot-through, oscillation, etc.) at the actual application conditions. Too small RG may cause failure of IGBTs or FWDs. RG selection higher than its lower recommended value is strongly recommended. RG selection higher than its upper recommended value is not restricted, unless switching loss increase or any unexpected malfunction (arm-shoot-through, oscillation, etc.) are carefully checked.

Since the surge voltage will change depending on the wiring inductance of the equipment and the snubber circuit etc., the optimum value varies depending on the user. In order to maximize the device performance, it is recommended to individually set the gate resistance on turn-on side and turn-off side.

9.3. Gate drive power supply

A gate drive power supply that can supply sufficient gate current and drive power is necessary. Once the gate voltage and gate resistance R_G are determined, the gate current of the drive circuit and the required drive power are calculated as follows.

(1) Average current (When driven with V_{GE} = ±15V, excluding consumption by drive circuit)

Average drive current (Typ) = Q_G (-15V \rightarrow +15) × fc

 Q_G : gate charge amount (-15V \rightarrow +15V)

fc: Switching carrier frequency

Figure 9-6 shows the characteristics of the gate charge of the CM600DX-24T.



Figure 9-6. Gate voltage and Gate Charge

(2) Peak output current

$$I_{Gpeak} = \frac{(+V_{GE}) - (-V_{GE})}{R_G(external) + r_g(module\ internal)}$$

Note) In actual practice, the peak current value may be smaller than the calculated value due to the delay of the drive circuit, the inductance of the drive wiring, etc.

(3) Average drive power

$$= \frac{1}{T} \int V \bullet idt$$

= $(+V_{GE}) \frac{1}{T_1} \int idt + (-V_{GE}) \frac{1}{T_2} \int idt$
= $(+V_{GE}) \bullet Q_G \bullet fc + (-V_{GE}) \bullet Q_G \bullet fc$
= $((+V_{GE}) + (-V_{GE})) \bullet Q_G \bullet fc$

9.4. Dead time setting

In the inverter circuit etc., it is necessary to set the upper and lower arm dead time in the sequence of the drive signals in order to prevent upper and lower arm short circuit.



Figure 9-7. Upper and lower arm dead time

The required dead time depends on the switching time when the upper and lower arms turn on and turn off. Therefore, the required dead time will change depending on the gate resistance value. If the dead time is too short, upper and lower arms are short-circuited in the same phase and short-circuit current flows, so there is a possibility of thermal destruction. After testing with the actual unit, please set the dead time appropriately.

9.5. Short Circuit Protection

The short-circuit SOA (safe operation area) is defined in the data sheet.

(1) Conditions for short-circuit SOA (Please refer to data sheet for safe operation area)

·650V withstand voltage devices

V_{CC}≦400V, V_{GE}=±15V, T_{vj} = 25 - 150°C, R_G=recommended gate resistance value, short time t_w≦8µs, non-repetitive

·1200V withstand voltage devices

V_{CC}≦800V, V_{GE}=E0V, VT_{vj} = 25 - 150°C, R_G=recommended gate resistance value, short time t_w≦8µs, non-repetitive

The definition of short-circuit time t_w is shown in Figures 9-8 and 9-9.



Figure 9-8. Definition of the short-circuit time tw in the case of arm short circuit



Figure 9-9. Definition of the short-circuit time in the case of load short-circuit tw

(2) Short-circuit protection method

As a method of simply detecting the occurrence of a short circuit without detecting the collector current, a method of detecting the on-voltage (V) when the IGBT is on is often used. IGBT drivers etc. with built-in short circuit protection function are also on the market. The short-circuit protection circuit built in the IGBT driver judges the short circuit condition when the gate output is on and the collector potential of the IGBT is high, then shuts off the gate voltage. Since surge voltage (C-E) becomes high when cutting off a large current quickly, we recommend a method to suppress the gate voltage softly to suppress the surge voltage (C-E).



Figure 9-10. Example of short-circuit protection of IGBT driver

(3)Protection by fuse

Switching element/diode/capacitor destruction may cause secondary electrical damage to the commercial power supply or the system unit. In order to prevent the secondary damage, attach fuses or a breaker to the appropriate location. The references of the fuse location are shown below. Select properly rated fuse considering using voltage and blocking current.

Examples



9.6. Parallel connection of IGBT modules

(1) Parallel Operation

The following sub-sections outline the basic requirements and considerations for parallel operation of 7th generation IGBT module of dual switch configuration with ratings of 200A or more. 7th generation IGBT module lineups paralleling-specification type which is specially designated for parallel use.

V_{CEsat}-I_C characteristics of the 7th generation IGBT modules signify a positive with temperature coefficient. This feature (positive temperature coefficient) facilitates the reduction in the imbalance of the collector current between paralleled devices. When the junction temperature of IGBT rises, the V_{CEsat} increases and the collector current reduces accordingly.



Figure 9-11. VCEsat characteristics of CM300DX-24T

When two 7th generation IGBT modules with parallel specification are paralleled, the ratio of the maximum static current imbalance will be restricted to $\pm 15\%$. Using modules from the same lot number in parallel is recommended since a smaller deviation in the V_{CEsat} results in a smaller ratio of the static current imbalance between two modules. (Please inquire of your sales contact the detail of the parallel specification)

As the number of modules connected in parallel increases, there is a possibility for any one single module to experience a high collector current. When modules are paralleled, calculate the derating current with formula shown below:

$$\begin{cases} 1 - \frac{(n-1) \times \frac{1-x}{1+x} + 1}{n} \end{cases} \times 100\% \\ & \text{Where } n: \text{ number of paralleled modules} \\ & \text{x: ratio of static current imbalance} \end{cases}$$

Matching V_{CEsat} is effective for maintaining good static steady state current balance. Gate drive conditions and power circuit layout have the greatest impact on dynamic current balance between paralleled devices. The IGBT modules should be connected with a short and symmetric connection with low impedance to the application circuit in order to minimize the current imbalance.

Layout of main circuit

- Circuit connections should be low inductance and laid out symmetrically for balanced inductance.
 Difference in the circuit inductance between each device may result in current imbalance.
 Asymmetrically high power loss may occur on one particular device and cause thermal destruction. (Figure 9-12)
- Use snubber circuit for each module individually and reduce circuit inductance in order to minimize surge voltage.

<Example of Imbalanced current>

Collector current through each device has a large deviation due to an imbalance in the circuit inductance between devices.





Collector current flows symmetrically due to balanced

<Example of balanced current>

circuit inductance between devices

Figure 9–12. Current imbalance caused by an asymmetric main circuit inductance

Gate Drive Circuit

- Uniform impedance of each gate drive circuit. In case the difference in the impedance consisting of gate resistance and stray inductance is high, current imbalance may occur.
- Use short and tightly-twisted wires of equal length.
- Gate resistance should not be too high.
- Avoid running the wiring of drive circuit in parallel to main circuit.
- Use gate resistor for each device individually to prevent gate oscillation. (Figure 9-13)

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Insert a low value resistance (e.g. 0.1 Ω) or ferrite core in the emitter wiring of the gate drivers in case an inductive current flows in the loop of the main emitter wiring and the gate driver wiring. This loop current may cause a difference in the switching speeds between paralleled devices by influencing the instantaneous gate voltage. (Figure 9-14)

<Example of Imbalanced current> Only a single gate resistor is employed to connect the gates of the paralleled devices.



<Example of Current balance> Use gate resistors for each device individually to prevent gate oscillations



Figure 9-13. Measures to limit gate oscillation

<Example of Imbalanced current> Inductive current flows through the drive circuit via emitter connection due to a difference in the value of the inductances Ls1 and Ls2.



<Example of Current balance>

Insert resistors (Rs =0.1ohm) or ferrite core in emitter wiring of the gate drive circuit to limit the inductive current flow.



Figure 9-14. Measures to limit inductive current in emitter wiring

10. Power loss and heat dissipation design

10.1. How to calculate the power loss

Loss calculation of the power module

In order to use the power module safely, it is necessary to calculate the power loss and the junction temperature under the conditions to be used, and to use the module within the absolute ratings. When selecting a power module, you can download and use simulation software from our website.

Download site: http://www.mitsubishielectric.com/semiconductors/simulator/index.html

Please click "Register" on the page, and after entering the necessary information, the download page will be displayed. *: Supported OS is Windows® 98SE or later only.

For the usage of the software, please download the manual "POWER LOSS SIMULATION Ver. * User's Manual"

Power loss and junction temperature

It is very important to understand the junction temperature when using the IGBT module. How to obtain the junction temperature is explained by taking the waveform of Figure 10-1 as an example. The calculation of the IGBT part is shown below as an example, but the calculation method of the diode part is basically the same. Regarding the temperature rise, please be careful not only to the maximum rating, but also to the power cycle lifetime due to temperature swing.



Figure 10-1. Determination of the junction temperature

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Power loss

To determine the junction temperature, the user will need to know the losses of the IGBT module. The loss per pulse should be first determined. The loss of one pulse is considered divided into steady-state and switching losses.

(1) Steady-state loss

Using a graph of V_{CEsat} vs. I_C characteristics, calculate the energy (J).

$$E_{(sat)} = \frac{I_{C1} \times V_{CEsat1} + I_{C2} \times V_{CEsat2}}{2} \times t_{w1}$$

Note) The above expression is simplified. Originally described as:

$$E_{(sat)} = \int_{0}^{tw'} Ic(t) \bullet V_{CE}(t) dt$$

In this case, data of T_{vj} = 150°C is used for the graph of V_{CEsat} vs. I_C.

(2) Switching losses

The switching loss is obtained from the actual waveform by the piecewise quadrature.

$$E_{on}/E_{off} = \int_{ta}^{tb} I_C(t) \bullet V_{CE}(t) dt = \frac{1}{n} \sum_{n=1}^{n} P_n \times (t_b - t_a)$$
 n: number of divisions (Equally divide the section of ta - tb, averaging the power loss for each point)

by summing (1) and (2), the loss of the IGBT E_1 per pulse is:

$$E_1 = E_{sat} + E_{on} + E_{off}$$

Also, the loss of the FWD section is calculated similarly to the IGBT section.

$$E_{rr} = \int_{ta}^{tb} I_E(t) \bullet V_{EC}(t) dt = \frac{1}{n} \sum_{n=1}^{n} P_n \times (t_b - t_a)$$

Refer to the integration range of switching loss as follows



Turn-on





Recovery

Figure 10-3. Integration range of switching loss





Figure 10-2. Steady-state Loss and Switching Loss

(3) Calculate the average power loss.

The average power loss in one pulse is

$$P_1 = \frac{E_1}{t_{w1}} \quad (W)$$

If the waveform in Figure 10-1 is approximated as a rectangular wave with respect to power, it is represented as shown in Figure 10-4.



Figure 10-4. Concept of Average Power Loss 1

Calculate the average power loss in the period tw2. (See Figure 10-5)

 $P_{av} = \frac{E_1}{t_{w2}} \times N \quad \mbox{(W)} \qquad \qquad \mbox{N: number of pulses within the t_{w2} period}$



Figure 10-5. Concept of Average Power Loss 2

Calculate the overall average power loss. (See Figure 10-6)

 $PAV = Pav \times \frac{tw2}{T2}$ (W)



Figure 10-6. Concept of Average Power Loss 3

10.2. Calculation of temperature rise

Calculate the junction temperature using P_1 , P_{av} , P_{AV} obtained above.

(1) $t_{w1} \ll 1ms$

In the approximation in Figure 10-5, the junction temperature is highest when the case temperature (or heat sink temperature) reaches steady state and the time when t_{w2} expires. (See Figure 10-7)



Maximum rise point of T_{vj}

Figure 10-7. Concept of the junction temperature 1



Maximum rise point of T_{vj}

Figure 10-8. Concept of junction temperature 2

Assuming that the temperature difference between the junction and case is $\Delta T_{(j-c)}$

 $\Delta T_{(j-c)} = R_{th(j-c)} \times j_{AV} - Z_{th(j-c)} @t_{w2} \times 2_{AV} + Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} \times P_{av} = R_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \otimes Z_{th(j-c)} \otimes j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-$

 $Z_{th(j-c)}@t_{w2}$Transient thermal impedance at the time of t_{w2} between junction and case

Using the above calculated $\Delta T(j-c)$, the junction temperature can be calculated as

 $T_{vj} = T_c + \Delta T_{(j-c)}$ (Here Tc is measurement value at the position of just under chip by e.g. thermocouple)

Also, in order to keep the T_{vj} lower than the maximum rating T_{vjmax} = 175°C, the allowable case temperature rise can be calculated as:

$$T_{C(max)} = 175 - \Delta T_{(j-c)}$$
.

Please also note that the case temperature T_{C} should not exceed its maximum rating $T_{C\text{max}}.$

(2) Overload from steady-state operation

In this case, ripple due to P_{OL} must also be taken into consideration. As in the case of (1), perform a square wave approximation as shown in Fig. 10-9.





 $\Delta T_{(j-c)} = R_{th(j-c)} \times j_{AV} - Z_{th(j-c)} @t_{w2} \times 2_{AV} + Z_{th(j-c)} @t_{w2} \times P_{av} - Z_{th(j-c)} @t_{w3} \times P_{av} + Z_{th(j-c)} @t_{w3} \times 3_{OL} + Z_{th(j-c)} @t_{w3} \times 2_{AV} + Z_{th(j-c)} @t_{w3} \times 2$

 $= R_{th(j-c)} \times j_{AV} + (P_{av} - P_{AV}) \times Z_{th(j-c)} @t_{w2} + (P_{OL} - P_{av}) \times Z_{th(j-c)} @t_{w3}$

Rth(j-c) j-chermal resistance between junction and case

 $Z_{th(j-c)}$ $@t_{w2}$ 2-Transient thermal impedance at the time of t_{w2} between junction and case

 $Z_{th(j-c)}@t_{w3}$ -cTransient thermal impedance at the time of t_{w3} between junction and case

Using the above calculated $\Delta T_{(j-c)}$, the junction temperature can be calculated as

 $T_{vj}=T_c+\Delta T_{(j-c)}$ (Here Tc is measurement value at the position of just under chip by e.g. thermocouple)

Please also note that the case temperature T_C should not exceed its maximum rating T_{Cmax} .

(3) Transient thermal impedance

Transient thermal impedance is calculated by the following equation.

The details of $R_{th(j-c)}$, R_i and τ_i are written in the each product data sheet.

$$Z_{th(j-c)} = R_{th(j-c)} \times \sum_{i=1}^{4} \left\{ R_i \times \left(1 - e^{-\frac{t}{\tau_i}} \right) \right\}$$

Heat sink selection

Figure 10-10 shows the thermal equivalent circuit when multiple modules are mounted on one heat sink. In this equivalent circuit, the temperature of the heat sink is $T_s = T_a + (P_{Q(AV)} + P_{D(AV)}) \times N \times R_{th(s-a)}$



T_a:Ambient temperature

 $P_{Q(AV)}$: average power loss of transistor part(W)

 $P_{D(AV)} {:} average \ power \ loss \ of \ diode \ part \ \ (W)$

N:number of modules

 $R_{th(s\mbox{-}a)}\mbox{:}thermal resistance from heatsink to ambient(K/W)$

Figure 10-10. Thermal equivalent circuit

In this equivalent circuit, case temperature T_C is calculated as:

$T_{C} = T_{s} + (P_{Q(AV)} + P_{D(AV)}) \times R_{th(c-s)}$

 $= T_a + (P_{Q(AV)} + P_{D(AV)}) \times N \times R_{th(s-a)} + (P_{Q(AV)} + P_{D(AV)}) \times R_{th(c-s)}$

Rth(c-s): Contact thermal resistance between case and heat sink

Heat sink should be selected so that the calculated Tc above not exceed the value $T_{C(max)}$ which is obtained in 10.2.(1). Therefore, the required thermal resistance of heat sink is calculated as:

 $T_{C} = T_{a} + (P_{Q(AV)} + P_{D(AV)}) \times N \times R_{th(s-a)} + (P_{Q(AV)} + P_{D(AV)}) \times R_{th(c-s)} < T_{C(max)}$

$$\therefore R_{th(s-a)} < \frac{T_{C(max)} - T_a - (P_{Q(AV)} + P_{D(AV)}) \times R_{th(c-s)})}{(P_{Q(AV)} + P_{D(AV)}) \times N}$$

The $T_{C(max)}$ value obtained from the power loss of the IGBT part should be compared with the value obtained from the power loss of the diode part, and the lower $T_{C(max)}$ value should be applied.

(However, please also note that the case temperature T_C should not exceed its maximum rating T_{Cmax})

General precautions when applying to inverters

The above calculation method is a simplified calculation method. Please pay attention to the following when conducting detailed calculations.

(1) One period of output current should be divided into multiple pulses and it is necessary to calculate the the power loss and the temperature based on actual "PWM duty", "Output current" and " V_{CEsat} , V_{EC} , E_{on} , E_{off} , E_{rr} at the output current" and to accumulate the results.

② PWM duty depends on the signal generation method (modulation method).

③ The relationship between the output current waveform (or output current) and the PWM duty depends on various factors such as signal generation method (modulation method), load, etc. Therefore the output current should be based on actual measured waveforms.

(4) For V_{CEsat} and V_{EC} , use the value of T_{vj} = 150°C.

(5) For E_{on} , E_{off} , and E_{rr} , the value at $T_{vj} = 150^{\circ}C$ under half bridge operation is used.

General precautions for thermal design

① It is necessary to consider the operating conditions that make the worst case losses.

- Temperature change due to output current frequency/period should be taken into account.
 (Approximately +30% at 60 Hz. When the output current fundamental frequency is low (several Hz) and lasts several seconds, it will be similar as the temperature when DC continuous switching operation at its peak current.
- (3) In addition to T_{vjmax} , the influence of power cycles and thermal cycles must also be taken into consideration.

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